

The potential of dense Landsat time series to characterize historical dynamics and monitor future disturbances in human-modified rainforests of Indonesia

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1. Motivation

Forests are central in the breakthrough 2015 Paris climate agreement. It has been estimated that tropical forest conservation and restoration could provide half of the target net emission reduction. The tropical region of insular South East Asia, notably the country of Indonesia, is a global hotspot of deforestation. Satellite remote sensing is the only viable means to map and monitor the vast Indonesian rainforests, to support REDD+ Tier-3 Measuring, Reporting, and Verifying requirements and the reporting principles of consistency, accuracy, comparability, completeness, and transparency. Landsat data have the appropriate spatial resolution (30 m) to capture human influence on the forest landscape, as well as provide the longest, rigorously calibrated time series (30 years+) which can aid in estimating Reference Emission Levels and operating a National Forest Monitoring System. Previous forest change detection studies using Landsat Time Series (LTS) in Indonesia were typically based on annual or epochal composites, and thus were yet to fully exploit the dense (i.e., “all available data”) LTS potential for sub-annual detection, and may miss transient changes due to the rapid vegetation regrowth. More recently, there have been significant advances in the development of dense time series algorithms. The objective of this study is to investigate the potential of using LTS data and data-driven dense time series algorithms for the detection of deforestation events at sub-annual time scales in Indonesian tropical rainforests.

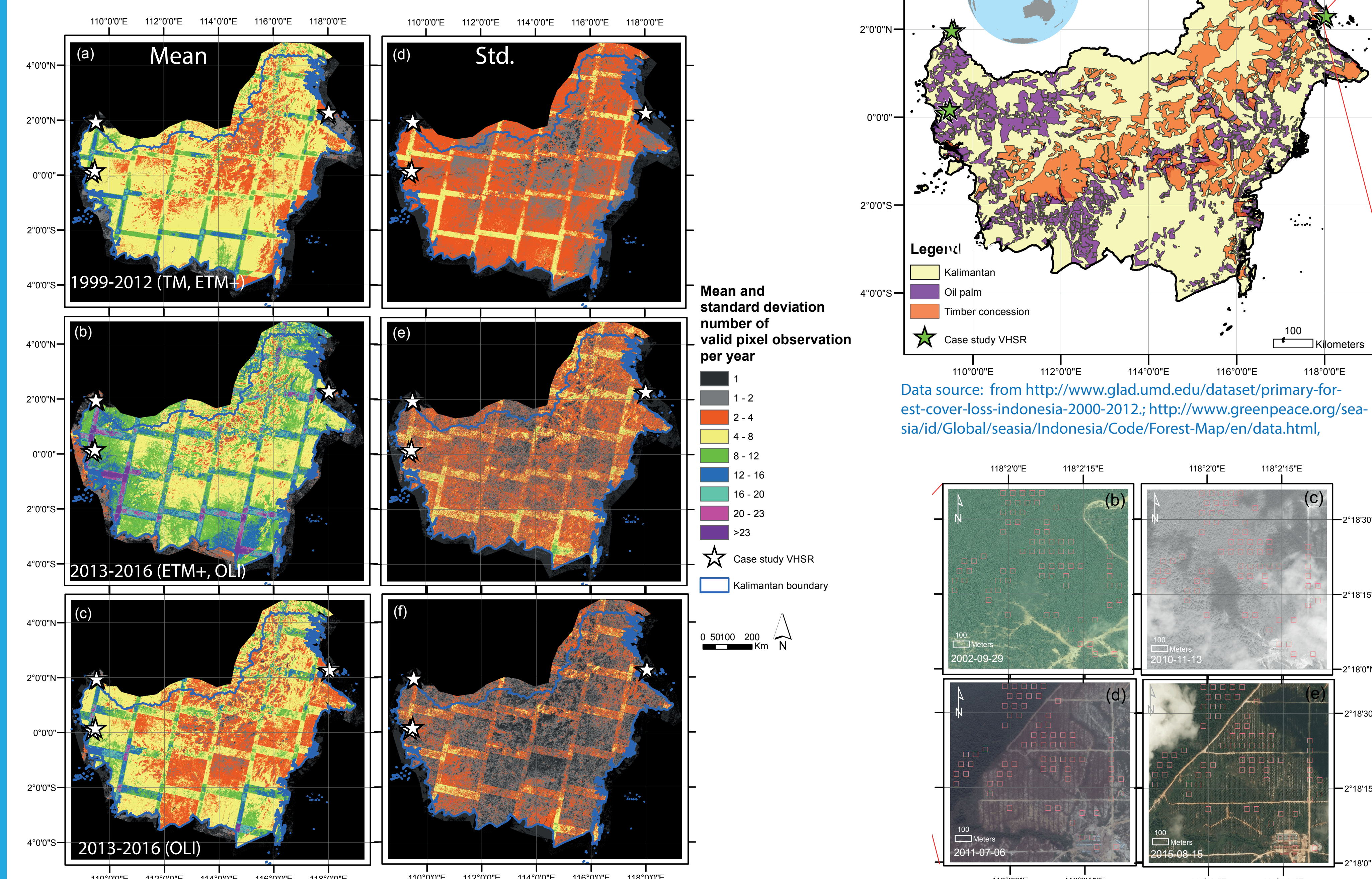
2. Satellite and reference data

We used the cloud-based platform google Earth Engine (EE) to retrieve all available Landsat surface reflectance images in the USGS archive, including Landsat-5 TM (1984-2012), Landsat-7 ETM+ (1999-2016), and Landsat-8 OLI (2013-2016) sensors, as temporal stacks for our study locations. Clouds and shadows were masked using the CFMask product.

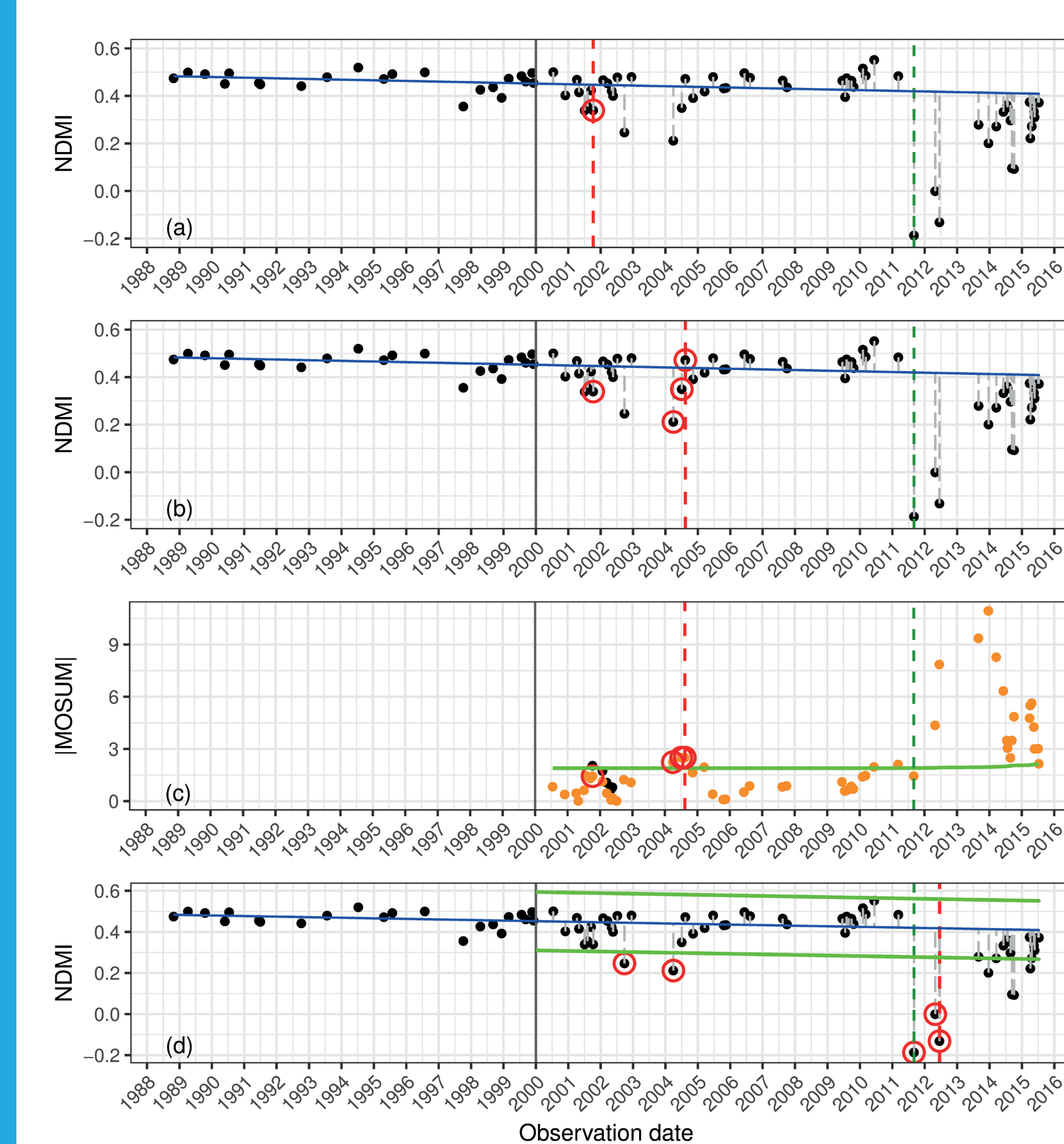
We used the normalized difference moisture index (NDMI) as it shows high sensitivity (most clear signal) in response to deforestation events in our study area, with signal change magnitude most visibly larger than ephemeral noise (e.g., un-masked clouds).

Reference sample pixels (435 samples: 227 “deforestation” samples and 208 “forest-remaining-forest” samples) were interpreted from six very high spatial resolution images obtained through Digital Globe viewing service.

Gorelick, N.; Hancher, M.; Dixon, M.; Ilyushchenko, S.; Thau, D.; Moore, R. Google Earth Engine: Planetary-scale geospatial analysis for everyone. *Remote Sensing of Environment* 2017, 202, 18–27



3. Dense time series algorithms for deforestation detection



Algorithm 1: BFAST Monitor
Fit a trend model to the history period ($t = 1, \dots, n$). Monitor discrepancies (i.e., moving sum of residuals, MOSUM) between model predictions and observations in the monitoring period ($t = n+1, \dots, N$). Breakpoint signalled if MOSUM (*process*) exceeds the statistical boundary.

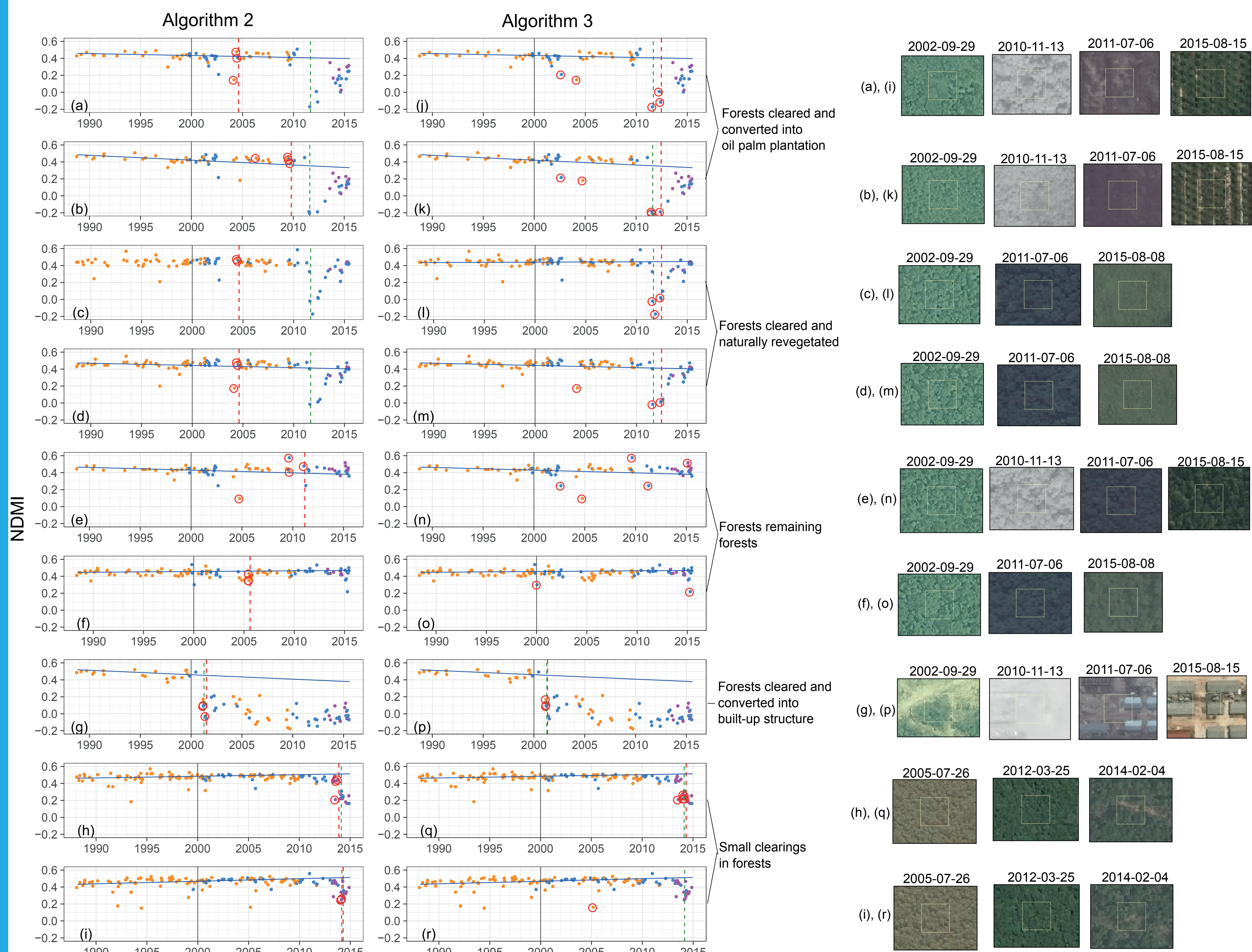
Algorithm 2: BFAST Monitor with Consecutive Anomalies Criterion (CAC)
for $t = n+1, \dots, N - cons + 1$ do
if *process* $>$ *boundary*, then
 $flag_t = \text{"changeFlagged"}$
for $j = t, \dots, (t + cons - 1)$ do
if all(*process* $>$ *boundary*) and
($T_{t+cons-1} - T_t) \leq 2$ then
 $flag_{t+cons-1} = \text{"changeConfirmed"}$
 $flag_t = \text{"changeFirstFlagged"}$
break
else
 $flag_t = \text{"noise"}$
end if
end for
end for
end for

boundary = $k \times RMSE_{history}$

Verbesselt, J.; Zeileis, A.; Herold, M. Near real-time disturbance detection using satellite image time series. *Remote Sensing of Environment* 2012, 123, 98–108.

Zhu, Z.; Woodcock, C.E. Continuous change detection and classification of land cover using all available Landsat data. *Remote Sensing of Environment* 2014, 144, 152–171

4. Demonstrations of the deforestation detection algorithms



5. Spatial and temporal accuracies

Algorithm	History denoised	cons	k	update MOSUM	OA (%)	UA (%)*	PA (%)*	MTL (days)	MTL (# obs)
1	No	NA	NA	NA	43.0	32.6	100.0	24	1
1	Yes	NA	NA	NA	8.3	5.0	100.0	0	0
2	Yes	3	NA	No	15.2	9.8	100.0	128	2
2	Yes	3	NA	Yes	15.9	9.9	100.0	128	2
2	No	3	NA	No	51.7	40.3	99.3	136	3
2	No	3	NA	Yes	53.3	41.3	99.3	132	3
3	No	3	4	NA	93.8	94.5	93.2	112	2
3	Yes	3	4	NA	94.7	95.0	94.6	112	2
3	No	2	5.5	NA	88.7	87.0	89.9	40	1
3	Yes	2	5.5	NA	89.0	85.3	92.7	40	1

* deforestation class

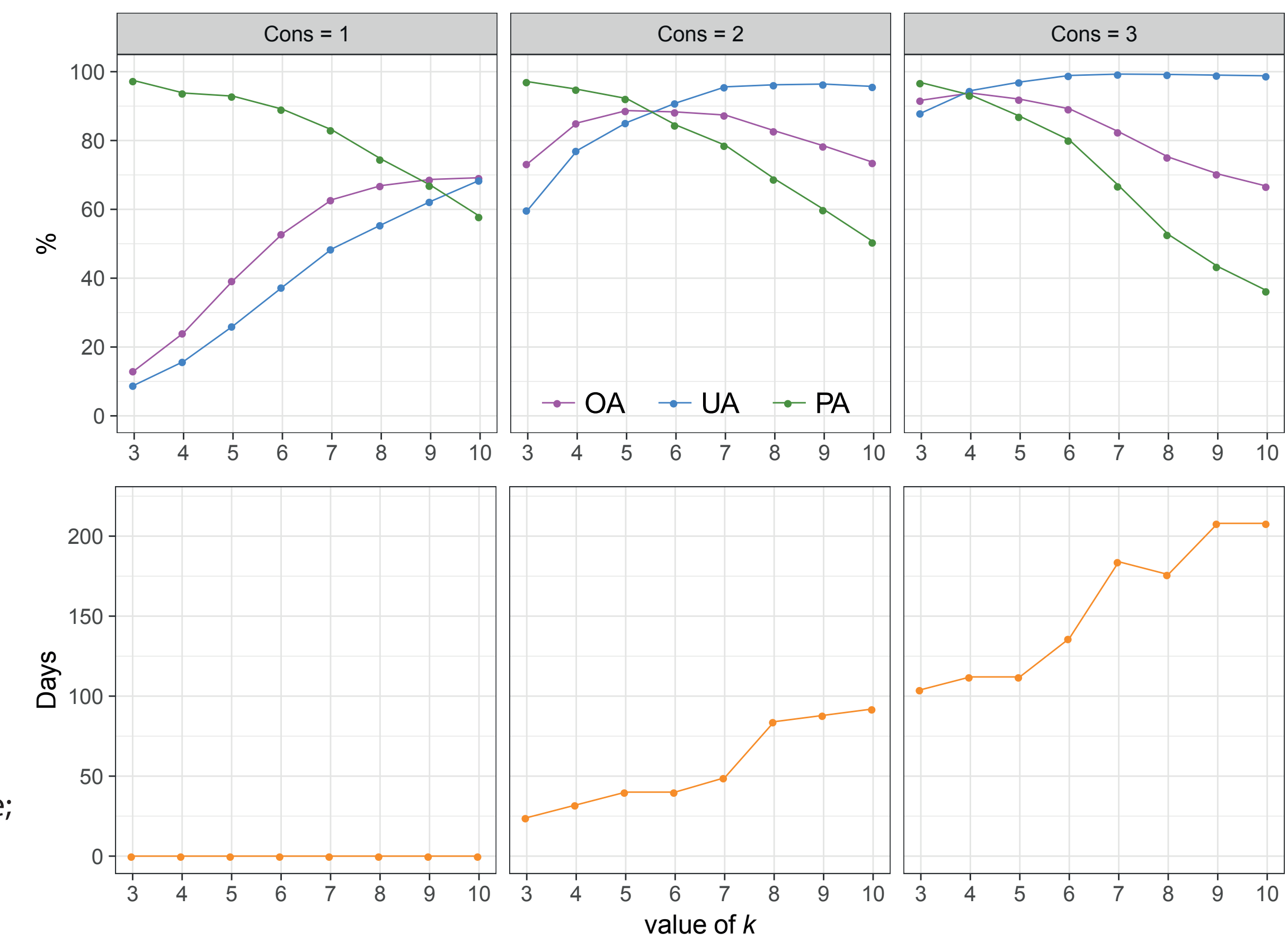
Overall accuracy, OA(%) = $100 \times (TP + TN) / (TP + TN + FP + FN)$

User's accuracy, UA(%) = $100 \times (TP / (TP + FP))$

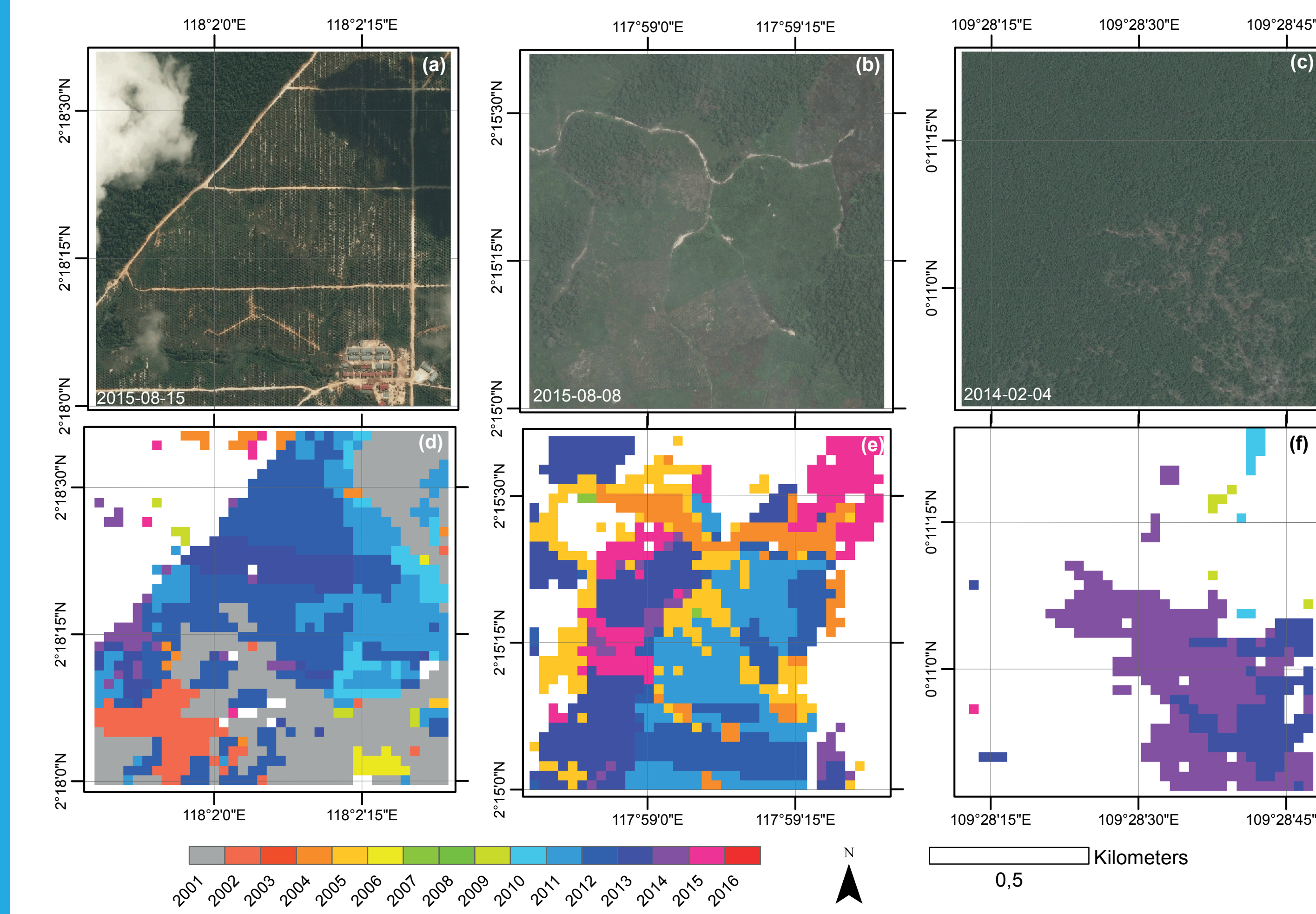
Producer's accuracy, PA(%) = $100 \times (TP / (TP + FN))$

Median temporal lag, MTL = median($T_{conf} - T_{ref}$)

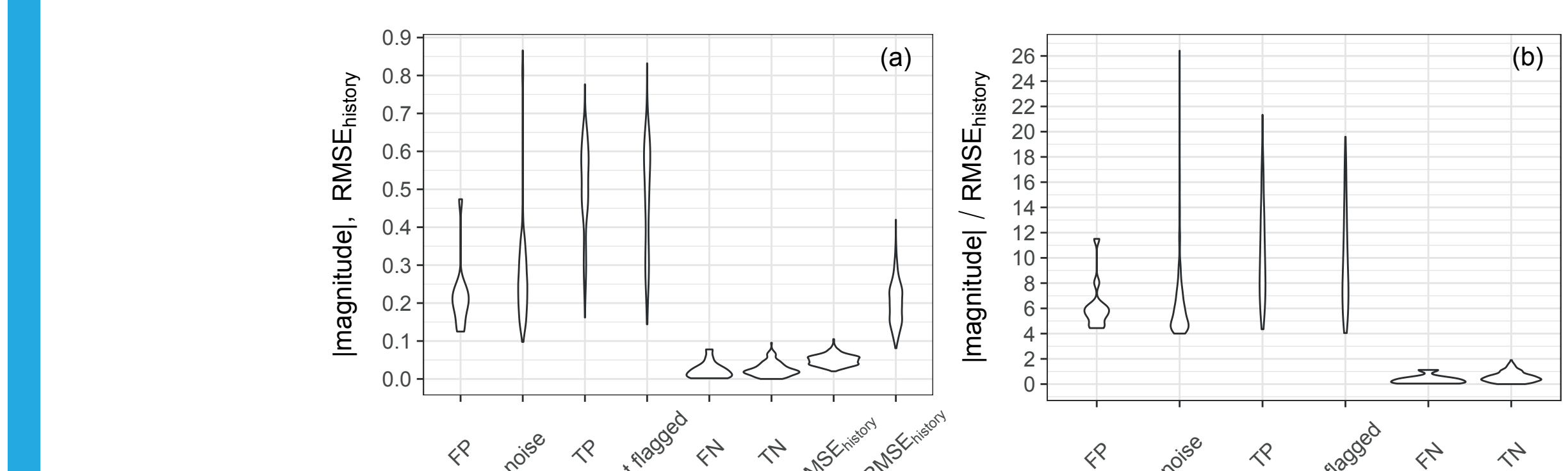
TP: true positive; TN: true negative; FP: false positive; FN: false negative; T_{conf} : confirmed date (algorithm); T_{ref} : reference date



6. Wall-to-wall assessment



7. Analysis of change magnitude



9. Outlook

- Magnitude-informed spatio-temporally adaptive *cons*.
- Publish the algorithm codes in public repository.
- Collect large reference sample representative of the larger Kalimantan area, to evaluate the robustness of the methodology for producing large area estimates and statistics.
- Investigate spectral-temporal features in dense LTS data to automate mapping of natural forests and plantations.
- Multisensor and ensemble (algorithm, indices) methods.

8. Conclusions

- Cloud-free observation density from combined TM, ETM+, and OLI sensors indicated feasibility of sub-annual deforestation mapping and monitoring.
- Frequent noise in LTS (due to remnant clouds), and its large range of change magnitude, caused high commission errors in the implemented BFAST Monitor (Algorithm 1).
- CAC improved the spatial accuracy of BFAST Monitor (in Algorithm 2); however, alternative decision boundary (Algorithm 3) dramatically improved the spatial accuracy.
- Therefore, the presented methodology based on dense LTS data and optimal Algorithm 3 is promising for use cases in which high spatial accuracy is a priority, such as carbon accounting for the purpose of REDD+ reporting.
- The temporal accuracy was not adequate for near-real-time monitoring. However, looking forward, combining Landsat data and the now fully-operational (i.e., global and systematic acquisitions realized) Sentinel-2A and Sentinel-2B will provide < 4 days revisit interval, thus potentially improves cloud-free observation density, and consequently the temporal accuracy of deforestation detection.

Acknowledgement. This study is funded by Aalto University (grant 91160122). Part of the research was developed in the Young Scientists Summer Program (YSSP) at the International Institute for Applied Systems Analysis (IIASA), Laxenburg, Austria with financial support from the Academy of Finland. This research was supported by the “RESTORE+: Addressing Landscape Restoration on Degraded Land in Indonesia and Brazil” project (www.restoreplus.org), carried out under the International Climate Initiative (IKI) of the German Federal Ministry for the Environment, Nature Conservation, Building and Nuclear Safety (BMUB); it received support from the project “Delivering Incentives to End Deforestation: Global Ambition, Private/Public Finance, and Zero-Deforestation Supply Chains” funded by the Norwegian Agency for Development Cooperation under agreement number QZA-0464 QZA-16/0218. Furthermore, the work has been funded by IIASA's Tropical Futures Initiative (TFI).